

Chapter 03.04

Newton-Raphson Method of Solving a Nonlinear Equation

After reading this chapter, you should be able to:

1. *derive the Newton-Raphson method formula,*
2. *develop the algorithm of the Newton-Raphson method,*
3. *use the Newton-Raphson method to solve a nonlinear equation, and*
4. *discuss the drawbacks of the Newton-Raphson method.*

Introduction

Methods such as the bisection method and the false position method of finding roots of a nonlinear equation $f(x) = 0$ require bracketing of the root by two guesses. Such methods are called *bracketing methods*. These methods are always convergent since they are based on reducing the interval between the two guesses so as to zero in on the root of the equation.

In the Newton-Raphson method, the root is not bracketed. In fact, only one initial guess of the root is needed to get the iterative process started to find the root of an equation. The method hence falls in the category of *open methods*. Convergence in open methods is not guaranteed but if the method does converge, it does so much faster than the bracketing methods.

Derivation

The Newton-Raphson method is based on the principle that if the initial guess of the root of $f(x) = 0$ is at x_i , then if one draws the tangent to the curve at $f(x_i)$, the point x_{i+1} where the tangent crosses the x -axis is an improved estimate of the root (Figure 1).

Using the definition of the slope of a function, at $x = x_i$

$$\begin{aligned} f'(x_i) &= \tan \theta \\ &= \frac{f(x_i) - 0}{x_i - x_{i+1}}, \end{aligned}$$

which gives

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \quad (1)$$

Equation (1) is called the Newton-Raphson formula for solving nonlinear equations of the form $f(x)=0$. So starting with an initial guess, x_i , one can find the next guess, x_{i+1} , by using Equation (1). One can repeat this process until one finds the root within a desirable tolerance.

Algorithm

The steps of the Newton-Raphson method to find the root of an equation $f(x)=0$ are

1. Evaluate $f'(x)$ symbolically
2. Use an initial guess of the root, x_i , to estimate the new value of the root, x_{i+1} , as

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

3. Find the absolute relative approximate error $|\epsilon_a|$ as

$$|\epsilon_a| = \left| \frac{x_{i+1} - x_i}{x_{i+1}} \right| \times 100$$

4. Compare the absolute relative approximate error with the pre-specified relative error tolerance, ϵ_s . If $|\epsilon_a| > \epsilon_s$, then go to Step 2, else stop the algorithm. Also, check if the number of iterations has exceeded the maximum number of iterations allowed. If so, one needs to terminate the algorithm and notify the user.

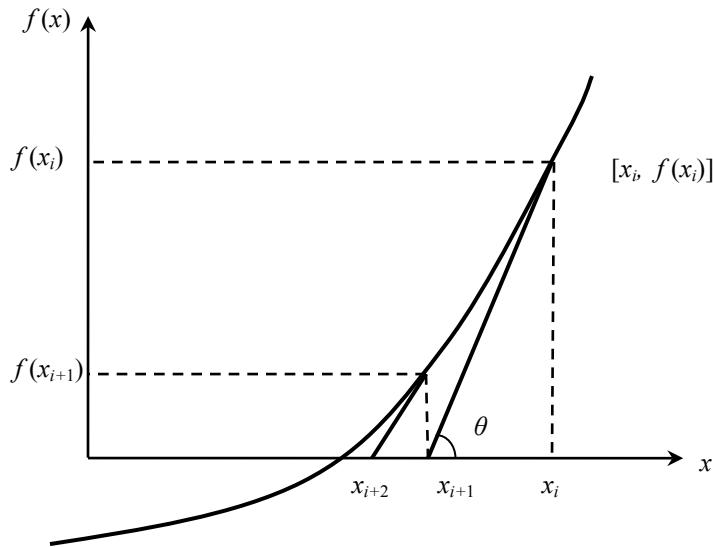


Figure 1 Geometrical illustration of the Newton-Raphson method.

Example 1

Thermistors are temperature-measuring devices based on the principle that the thermistor material exhibits a change in electrical resistance with a change in temperature. By measuring the resistance of the thermistor material, one can then determine the temperature. For a 10K3A Betatherm thermistor,

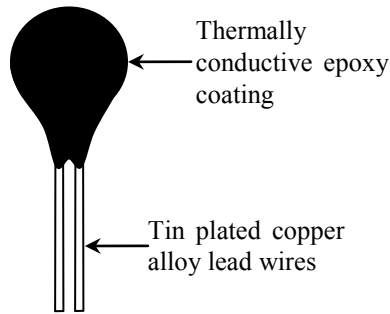


Figure 2 A typical thermistor.

the relationship between the resistance R of the thermistor and the temperature is given by

$$\frac{1}{T} = 1.129241 \times 10^{-3} + 2.341077 \times 10^{-4} \ln(R) + 8.775468 \times 10^{-8} \{\ln(R)\}^3$$

where T is in Kelvin and R is in ohms.

A thermistor error of no more than $\pm 0.01^\circ\text{C}$ is acceptable. To find the range of the resistance that is within this acceptable limit at 19°C , we need to solve

$$\frac{1}{19.01 + 273.15} = 1.129241 \times 10^{-3} + 2.341077 \times 10^{-4} \ln(R) + 8.775468 \times 10^{-8} \{\ln(R)\}^3$$

and

$$\frac{1}{18.99 + 273.15} = 1.129241 \times 10^{-3} + 2.341077 \times 10^{-4} \ln(R) + 8.775468 \times 10^{-8} \{\ln(R)\}^3$$

Use the Newton-Raphson method of finding roots of equations to find the resistance R at 18.99°C . Conduct three iterations to estimate the root of the above equation. Find the absolute relative approximate error at the end of each iteration and the number of significant digits at least correct at the end of each iteration.

Solution

Solving

$$\frac{1}{18.99 + 273.15} = 1.129241 \times 10^{-3} + 2.341077 \times 10^{-4} \ln(R) + 8.775468 \times 10^{-8} \{\ln(R)\}^3$$

we get

$$f(R) = 2.341077 \times 10^{-4} \ln(R) + 8.775468 \times 10^{-8} \{\ln(R)\}^3 - 2.293775 \times 10^{-3}$$

$$f'(R) = \frac{2.341077 \times 10^{-4} + 2.6326404 \times 10^{-7} \{\ln(R)\}^2}{R}$$

Let us take the initial guess of the root of $f(R) = 0$ as $R_0 = 15000$.

Iteration 1

The estimate of the root is

$$\begin{aligned}
 R_1 &= R_0 - \frac{f(R_0)}{f'(R_0)} \\
 &= 15000 - \frac{\left(2.341077 \times 10^{-4} \ln(15000) + 8.775468 \times 10^{-8} \{\ln(15000)\}^3 \right) - 2.293775 \times 10^{-3}}{\frac{2.341077 \times 10^{-4} + 2.6326404 \times 10^{-7} \{\ln(15000)\}^2}{15000}} \\
 &= 15000 - \frac{3.5383 \times 10^{-5}}{1.7230 \times 10^{-8}} \\
 &= 15000 - 2053.5 \\
 &= 12946
 \end{aligned}$$

The absolute relative approximate error $|\epsilon_a|$ at the end of Iteration 1 is

$$\begin{aligned}
 |\epsilon_a| &= \left| \frac{R_1 - R_0}{R_1} \right| \times 100 \\
 &= \left| \frac{12946 - 15000}{12946} \right| \times 100 \\
 &= 15.862\%
 \end{aligned}$$

The number of significant digits at least correct is 0, as you need an absolute relative approximate error of less than 5% for one significant digit to be correct in your result.

Iteration 2

The estimate of the root is

$$\begin{aligned}
 R_2 &= R_1 - \frac{f(R_1)}{f'(R_1)} \\
 &= 12946 - \frac{\left(2.341077 \times 10^{-4} \ln(12946) + 8.775468 \times 10^{-8} \{\ln(12946)\}^3 \right) - 2.293775 \times 10^{-3}}{\frac{2.341077 \times 10^{-4} + 2.6326404 \times 10^{-7} \{\ln(12946)\}^2}{12946}} \\
 &= 12946 - \frac{-2.6140 \times 10^{-6}}{1.9906 \times 10^{-8}} \\
 &= 12946 - (-131.32) \\
 &= 13078
 \end{aligned}$$

The absolute relative approximate error $|\epsilon_a|$ at the end of Iteration 2 is

$$\begin{aligned}
 |\epsilon_a| &= \left| \frac{R_2 - R_1}{R_2} \right| \times 100 \\
 &= \left| \frac{13078 - 12946}{13078} \right| \times 100 \\
 &= 1.0041\%
 \end{aligned}$$

The number of significant digits at least correct is 1, as the absolute relative approximate error is less than 5%.

Iteration 3

The estimate of the root is

$$\begin{aligned}
 R_3 &= R_2 - \frac{f(R_2)}{f'(R_2)} \\
 &= 13078 - \frac{\left(2.341077 \times 10^{-4} \ln(13078) + 8.775468 \times 10^{-8} \{\ln(13078)\}^3 \right) - 2.293775 \times 10^{-3}}{\frac{2.341077 \times 10^{-4} + 2.6326404 \times 10^{-7} \{\ln(13078)\}^2}{13078}} \\
 &= 13078 - \frac{-1.2914 \times 10^{-8}}{1.9710 \times 10^{-8}} \\
 &= 13078 - (-0.65519) \\
 &= 13078
 \end{aligned}$$

The absolute relative approximate error $|\epsilon_a|$ at the end of Iteration 3 is

$$\begin{aligned}
 |\epsilon_a| &= \left| \frac{R_3 - R_2}{R_3} \right| \times 100 \\
 &= \left| \frac{13078 - 13078}{13078} \right| \times 100 \\
 &= 0.0050097\%
 \end{aligned}$$

Hence the number of significant digits at least correct is given by the largest value of m for which

$$\begin{aligned}
 |\epsilon_a| &\leq 0.5 \times 10^{2-m} \\
 0.0050097 &\leq 0.5 \times 10^{2-m} \\
 0.010019 &\leq 10^{2-m} \\
 \log(0.010019) &\leq 2 - m \\
 m &\leq 2 - \log(0.010019) = 3.9992
 \end{aligned}$$

So

$$m = 3$$

The number of significant digits at least correct in the estimated root 13078 is 3.

Drawbacks of the Newton-Raphson Method

1. Divergence at inflection points

If the selection of the initial guess or an iterated value of the root turns out to be close to the inflection point (see the definition in the appendix of this chapter) of the function $f(x)$ in the equation $f(x) = 0$, Newton-Raphson method may start diverging away from the root. It may then start converging back to the root. For example, to find the root of the equation

$$f(x) = (x - 1)^3 + 0.512 = 0$$

the Newton-Raphson method reduces to

$$x_{i+1} = x_i - \frac{(x_i^3 - 1)^3 + 0.512}{3(x_i - 1)^2}$$

Starting with an initial guess of $x_0 = 5.0$, Table 1 shows the iterated values of the root of the equation. As you can observe, the root starts to diverge at Iteration 6 because the previous estimate of 0.92589 is close to the inflection point of $x = 1$ (the value of $f'(x)$ is zero at the inflection point). Eventually, after 12 more iterations the root converges to the exact value of $x = 0.2$.

Table 1 Divergence near inflection point.

Iteration Number	x_i
0	5.0000
1	3.6560
2	2.7465
3	2.1084
4	1.6000
5	0.92589
6	-30.119
7	-19.746
8	-12.831
9	-8.2217
10	-5.1498
11	-3.1044
12	-1.7464
13	-0.85356
14	-0.28538
15	0.039784
16	0.17475
17	0.19924
18	0.2

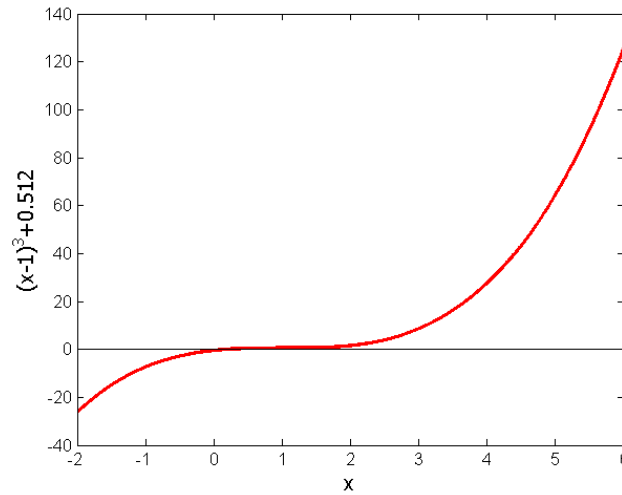


Figure 3 Divergence at inflection point for $f(x) = (x-1)^3 + 0.512$.

2. Division by zero

For the equation

$$f(x) = x^3 - 0.03x^2 + 2.4 \times 10^{-6} = 0$$

the Newton-Raphson method reduces to

$$x_{i+1} = x_i - \frac{x_i^3 - 0.03x_i^2 + 2.4 \times 10^{-6}}{3x_i^2 - 0.06x_i}$$

For $x_0 = 0$ or $x_0 = 0.02$, division by zero occurs (Figure 4). For an initial guess close to 0.02 such as $x_0 = 0.01999$, one may avoid division by zero, but then the denominator in the formula is a small number. For this case, as given in Table 2, even after 9 iterations, the Newton-Raphson method does not converge.

Table 2 Division by near zero in Newton-Raphson method.

Iteration Number	x_i	$f(x_i)$	$ \epsilon_a \%$
0	0.019990	-1.60000×10^{-6}	=====
1	-2.6480	18.778	100.75
2	-1.7620	-5.5638	50.282
3	-1.1714	-1.6485	50.422
4	-0.77765	-0.48842	50.632
5	-0.51518	-0.14470	50.946
6	-0.34025	-0.042862	51.413
7	-0.22369	-0.012692	52.107
8	-0.14608	-0.0037553	53.127
9	-0.094490	-0.0011091	54.602

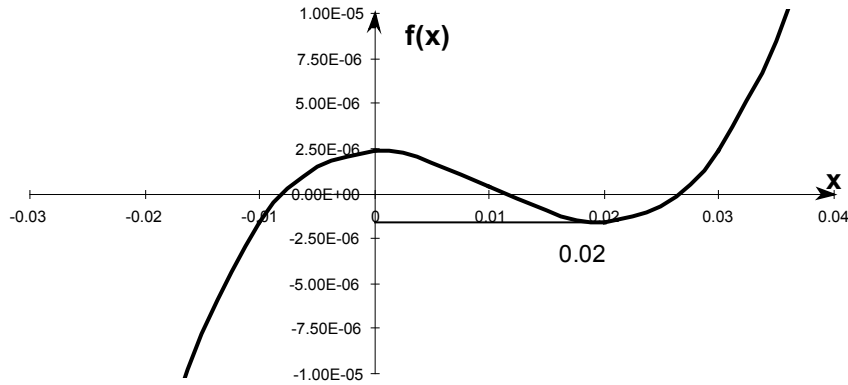


Figure 4 Pitfall of division by zero or a near zero number.

3. Oscillations near local maximum and minimum

Results obtained from the Newton-Raphson method may oscillate about the local maximum or minimum without converging on a root but converging on the local maximum or minimum. Eventually, it may lead to division by a number close to zero and may diverge.

For example, for

$$f(x) = x^2 + 2 = 0$$

the equation has no real roots (Figure 5 and Table 3).

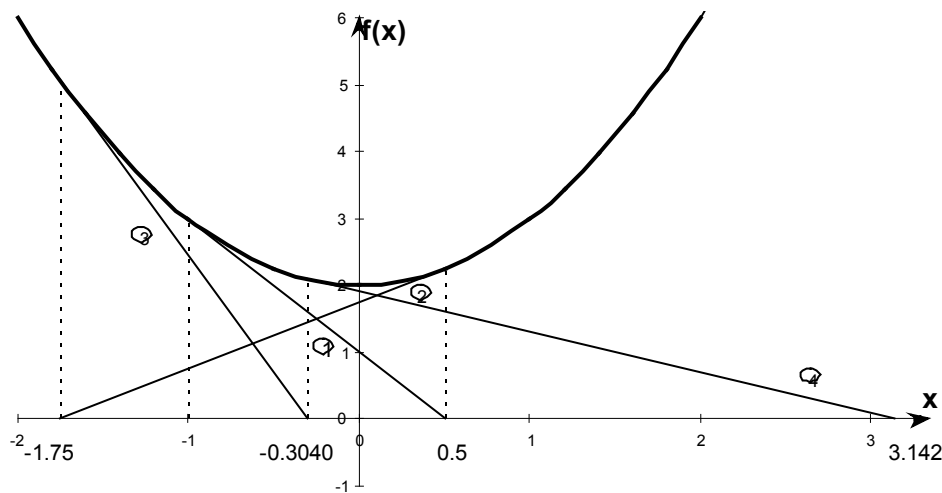


Figure 5 Oscillations around local minima for $f(x) = x^2 + 2$.

Table 3 Oscillations near local maxima and minima in Newton-Raphson method.

Iteration Number	x_i	$f(x_i)$	$ \epsilon_a \%$
0	-1.0000	3.00	—
1	0.5	2.25	300.00
2	-1.75	5.063	128.571
3	-0.30357	2.092	476.47
4	3.1423	11.874	109.66
5	1.2529	3.570	150.80
6	-0.17166	2.029	829.88
7	5.7395	34.942	102.99
8	2.6955	9.266	112.93
9	0.97678	2.954	175.96

4. Root jumping

In some case where the function $f(x)$ is oscillating and has a number of roots, one may choose an initial guess close to a root. However, the guesses may jump and converge to some other root. For example for solving the equation $\sin x = 0$ if you choose $x_0 = 2.4\pi = (7.539822)$ as an initial guess, it converges to the root of $x = 0$ as shown in Table 4 and Figure 6. However, one may have chosen this as an initial guess to converge to $x = 2\pi = 6.2831853$.

Table 4 Root jumping in Newton-Raphson method.

Iteration Number	x_i	$f(x_i)$	$ \epsilon_a \%$
0	7.539822	0.951	—
1	4.462	-0.969	68.973
2	0.5499	0.5226	711.44
3	-0.06307	-0.06303	971.91
4	8.376×10^{-4}	8.375×10^{-5}	7.54×10^4
5	-1.95861×10^{-13}	-1.95861×10^{-13}	4.28×10^{10}

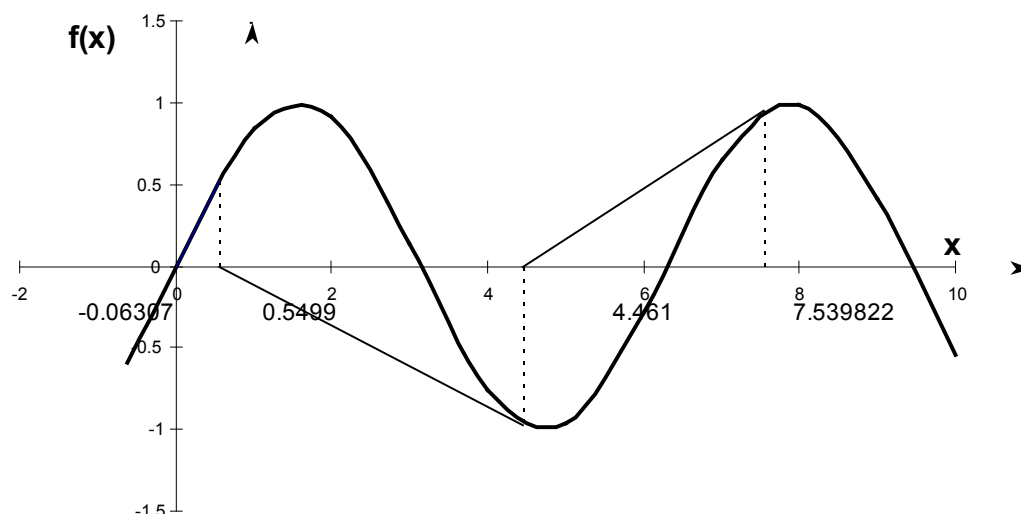


Figure 6 Root jumping from intended location of root for $f(x) = \sin x = 0$.

Appendix A. What is an inflection point?

For a function $f(x)$, the point where the concavity changes from up-to-down or down-to-up is called its inflection point. For example, for the function $f(x) = (x-1)^3$, the concavity changes at $x = 1$ (see Figure 3), and hence $(1,0)$ is an inflection point.

An inflection points MAY exist at a point where $f''(x) = 0$ and where $f''(x)$ does not exist. The reason we say that it MAY exist is because if $f''(x) = 0$, it only makes it a possible inflection point. For example, for $f(x) = x^4 - 16$, $f''(0) = 0$, but the concavity does not change at $x = 0$. Hence the point $(0, -16)$ is not an inflection point of $f(x) = x^4 - 16$.

For $f(x) = (x-1)^3$, $f''(x)$ changes sign at $x = 1$ ($f''(x) < 0$ for $x < 1$, and $f''(x) > 0$ for $x > 1$), and thus brings up the *Inflection Point Theorem* for a function $f(x)$ that states the following.

“If $f'(c)$ exists and $f''(c)$ changes sign at $x = c$, then the point $(c, f(c))$ is an inflection point of the graph of f .”

Appendix B. Derivation of Newton-Raphson method from Taylor series

Newton-Raphson method can also be derived from Taylor series. For a general function $f(x)$, the Taylor series is

$$f(x_{i+1}) = f(x_i) + f'(x_i)(x_{i+1} - x_i) + \frac{f''(x_i)}{2!}(x_{i+1} - x_i)^2 + \dots$$

As an approximation, taking only the first two terms of the right hand side,

$$f(x_{i+1}) \approx f(x_i) + f'(x_i)(x_{i+1} - x_i)$$

and we are seeking a point where $f(x) = 0$, that is, if we assume

$$f(x_{i+1}) = 0,$$

$$0 \approx f(x_i) + f'(x_i)(x_{i+1} - x_i)$$

which gives

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

This is the same Newton-Raphson method formula series as derived previously using the geometric method.

NONLINEAR EQUATIONS	
Topic	Newton-Raphson Method of Solving Nonlinear Equations
Summary	Text book notes of Newton-Raphson method of finding roots of nonlinear equation, including convergence and pitfalls.
Major	Electrical Engineering
Authors	Autar Kaw
Date	November 11, 2012
Web Site	http://numericalmethods.eng.usf.edu