Chapter 03.03 Bisection Method of Solving a Nonlinear Equation

After reading this chapter, you should be able to:

- 1. follow the algorithm of the bisection method of solving a nonlinear equation,
- 2. use the bisection method to solve examples of finding roots of a nonlinear equation, and
- 3. enumerate the advantages and disadvantages of the bisection method.

What is the bisection method and what is it based on?

One of the first numerical methods developed to find the root of a nonlinear equation f(x) = 0 was the bisection method (also called *binary-search* method). The method is based on the following theorem.

Theorem

An equation f(x) = 0, where f(x) is a real continuous function, has at least one root between x_{ℓ} and x_{n} if $f(x_{\ell})f(x_{n}) < 0$ (See Figure 1).

Note that if $f(x_\ell)f(x_u) > 0$, there may or may not be any root between x_ℓ and x_u (Figures 2 and 3). If $f(x_\ell)f(x_u) < 0$, then there may be more than one root between x_ℓ and x_u (Figure 4). So the theorem only guarantees one root between x_ℓ and x_u .

Bisection method

Since the method is based on finding the root between two points, the method falls under the category of bracketing methods.

Since the root is bracketed between two points, x_{ℓ} and x_{u} , one can find the midpoint, x_{m} between x_{ℓ} and x_{u} . This gives us two new intervals

- 1. x_{ℓ} and x_m , and
- 2. x_m and x_u .

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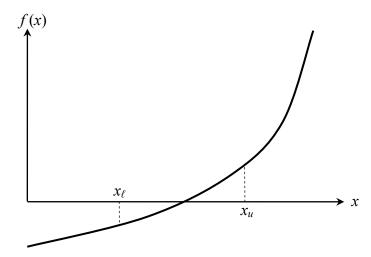


Figure 1 At least one root exists between the two points if the function is real, continuous, and changes sign.

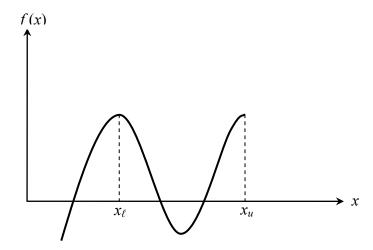


Figure 2 If the function f(x) does not change sign between the two points, roots of the equation f(x) = 0 may still exist between the two points.

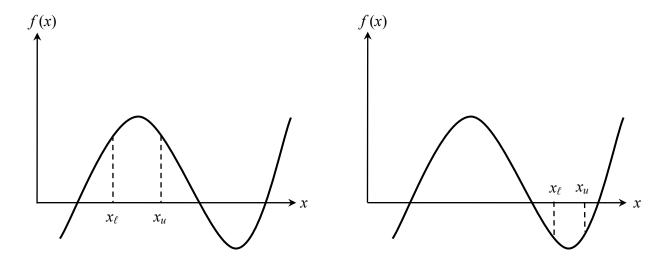


Figure 3 If the function f(x) does not change sign between two points, there may not be any roots for the equation f(x) = 0 between the two points.

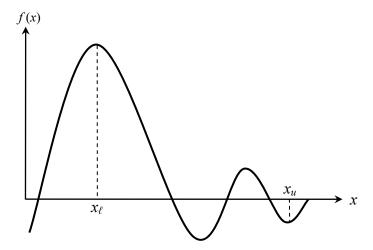


Figure 4 If the function f(x) changes sign between the two points, more than one root for the equation f(x) = 0 may exist between the two points.

Is the root now between x_ℓ and x_m or between x_m and x_u ? Well, one can find the sign of $f(x_\ell)f(x_m)$, and if $f(x_\ell)f(x_m) < 0$ then the new bracket is between x_ℓ and x_m , otherwise, it is between x_m and x_u . So, you can see that you are literally halving the interval. As one repeats this process, the width of the interval $[x_\ell, x_u]$ becomes smaller and smaller, and you can zero in to the root of the equation f(x) = 0. The algorithm for the bisection method is given as follows.

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Algorithm for the bisection method

The steps to apply the bisection method to find the root of the equation f(x) = 0 are

- 1. Choose x_{ℓ} and x_{u} as two guesses for the root such that $f(x_{\ell})f(x_{u}) < 0$, or in other words, f(x) changes sign between x_{ℓ} and x_{u} .
- 2. Estimate the root, x_m , of the equation f(x) = 0 as the mid-point between x_ℓ and x_u as

$$x_m = \frac{x_\ell + x_u}{2}$$

- 3. Now check the following
 - a) If $f(x_{\ell})f(x_m) < 0$, then the root lies between x_{ℓ} and x_m ; then $x_{\ell} = x_{\ell}$ and $x_m = x_m$.
 - b) If $f(x_{\ell})f(x_m) > 0$, then the root lies between x_m and x_u ; then $x_{\ell} = x_m$ and $x_u = x_u$.
 - c) If $f(x_{\ell})f(x_m) = 0$; then the root is x_m . Stop the algorithm if this is true.
- 4. Find the new estimate of the root

$$x_m = \frac{x_\ell + x_u}{2}$$

Find the absolute relative approximate error as

$$\left| \in_{a} \right| = \left| \frac{x_{m}^{\text{new}} - x_{m}^{\text{old}}}{x_{m}^{\text{new}}} \right| \times 100$$

where

 $x_m^{\text{new}} = \text{estimated root from present iteration}$

 x_m^{old} = estimated root from previous iteration

5. Compare the absolute relative approximate error $|\epsilon_a|$ with the pre-specified relative error tolerance ϵ_s . If $|\epsilon_a| > \epsilon_s$, then go to Step 3, else stop the algorithm. Note one should also check whether the number of iterations is more than the maximum number of iterations allowed. If so, one needs to terminate the algorithm and notify the user about it.

Example 1

You are working for a start-up computer assembly company and have been asked to determine the minimum number of computers that the shop will have to sell to make a profit. The equation that gives the minimum number of computers n to be sold after considering the total costs and the total sales is

$$f(n) = 40n^{1.5} - 875n + 35000 = 0$$

Use the bisection method of finding roots of equations to find the minimum number of computers that need to be sold to make a profit. Conduct three iterations to estimate the root of the above equation. Find the absolute relative approximate error at the end of each iteration and the number of significant digits at least correct at the end of each iteration.

Solution

Let us assume

$$n_{\ell} = 50, n_{u} = 100$$

Check if the function changes sign between n_{ℓ} and n_{u} .

$$f(n_{\ell}) = f(50) = 40(50)^{1.5} - 875(50) + 35000 = 5392.1$$

 $f(n_{u}) = f(100) = 40(100)^{1.5} - 875(100) + 35000 = -12500$

Hence

$$f(n_e)f(n_u) = f(50)f(100) = (5392.1)(-12500) < 0$$

So there is at least one root between n_{ℓ} and n_{μ} , that is, between 50 and 100.

Iteration 1

The estimate of the root is

$$n_{m} = \frac{n_{\ell} + n_{u}}{2}$$

$$= \frac{50 + 100}{2}$$

$$= 75$$

$$f(n_{m}) = f(75) = 40(75)^{1.5} - 875(75) + 35000 = -4.6442 \times 10^{3}$$

$$f(n_{\ell})f(n_{m}) = f(50)f(75) = (5392.1)(-4.6442 \times 10^{3}) < 0$$

Hence the root is bracketed between n_{ℓ} and n_{m} , that is, between 50 and 75. So, the lower and upper limits of the new bracket are

$$n_{\ell} = 50, n_{u} = 75$$

At this point, the absolute relative approximate error $|\epsilon_a|$ cannot be calculated, as we do not have a previous approximation.

Iteration 2

The estimate of the root is

$$n_{m} = \frac{n_{\ell} + n_{u}}{2}$$

$$= \frac{50 + 75}{2}$$

$$= 62.5$$

$$f(n_{m}) = f(62.5) = 40(62.5)^{1.5} - 875(62.5) + 35000 = 76.735$$

$$f(n_{\ell})f(n_{m}) = f(50)f(62.5) = (5392.1)(76.735) > 0$$

Hence, the root is bracketed between n_m and n_u , that is, between 62.5 and 75. So the lower and upper limits of the new bracket are

$$n_{\ell} = 62.5, n_{\mu} = 75$$

The absolute relative approximate error, $|\epsilon_a|$ at the end of Iteration 2 is

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$$\left| \in_{a} \right| = \left| \frac{n_{m}^{\text{new}} - n_{m}^{\text{old}}}{n_{m}^{\text{new}}} \right| \times 100$$
$$= \left| \frac{62.5 - 75}{62.5} \right| \times 100$$
$$= 20\%$$

None of the significant digits are at least correct in the estimated root

$$n_m = 62.5$$

as the absolute relative approximate error is greater that 5%.

Iteration 3

The estimate of the root is

$$n_{m} = \frac{n_{\ell} + n_{u}}{2}$$

$$= \frac{62.5 + 75}{2}$$

$$= 68.75$$

$$f(n_{m}) = f(68.75) = 40(68.75)^{1.5} - 875(68.75) + 35000 = -2.3545 \times 10^{3}$$

$$f(n_{\ell})f(n_{m}) = f(62.5)f(68.75) = (76.735)(-2.3545 \times 10^{3}) < 0$$

Hence, the root is bracketed between n_{ℓ} and n_{m} , that is, between 62.5 and 68.75. So the lower and upper limits of the new bracket are

$$n_{\ell} = 62.5, n_{u} = 68.75$$

The absolute relative approximate error $|\epsilon_a|$ at the end of Iteration 3 is

$$\left| \in_{a} \right| = \left| \frac{n_{m}^{\text{new}} - n_{m}^{\text{old}}}{n_{m}^{\text{new}}} \right| \times 100$$
$$= \left| \frac{68.75 - 62.5}{68.75} \right| \times 100$$
$$= 9.0909\%$$

Still none of the significant digits are at least correct in the estimated root of the equation, as the absolute relative approximate error is greater than 5%. The estimated minimum number of computers that need to be sold to break even at the end of the third iteration is 69. Seven more iterations were conducted and these iterations are shown in the Table 1.

Iteration	n_{ℓ}	n_u	$n_{\scriptscriptstyle m}$	∈ _a %	$f(n_m)$
1	50	100	75		-4.6442×10^3
2	50	75	62.5	20	76.735
3	62.5	75	68.75	9.0909	-2.3545×10^{3}
4	62.5	68.75	65.625	4.7619	-1.1569×10^3
5	62.5	65.625	64.063	2.4390	-544.68
6	62.5	64.063	63.281	1.2346	-235.12
7	62.5	63.281	62.891	0.62112	-79.483

62.695

62.598

62.646

0.31153

0.15601

0.077942

-1.4459

37.627

18.086

62.891

62.695

62.695

Table 1 Root of f(x) = 0 as a function of the number of iterations for bisection method.

At the end of the 10th iteration,

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$$|\epsilon_a| = 0.077942\%$$

Hence the number of significant digits at least correct is given by the largest value of m for which

$$\begin{aligned} \left| \in_{a} \right| &\leq 0.5 \times 10^{2-m} \\ 0.077942 &\leq 0.5 \times 10^{2-m} \\ 0.15588 &\leq 10^{2-m} \\ \log(0.15588) &\leq 2 - m \\ m &\leq 2 - \log(0.15588) = 2.8072 \end{aligned}$$

62.5

62.5

62.598

So

$$m = 2$$

The number of significant digits at least correct in the estimated root 62.646 is 2.

Advantages of bisection method

- a) The bisection method is always convergent. Since the method brackets the root, the method is guaranteed to converge.
- b) As iterations are conducted, the interval gets halved. So one can guarantee the error in the solution of the equation.

Drawbacks of bisection method

- a) The convergence of the bisection method is slow as it is simply based on halving the interval.
- b) If one of the initial guesses is closer to the root, it will take larger number of iterations to reach the root.
- c) If a function f(x) is such that it just touches the x-axis (Figure 6) such as

$$f(x) = x^2 = 0$$

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it will be unable to find the lower guess, x_{ℓ} , and upper guess, x_{u} , such that

$$f(x_{\ell})f(x_{\mu})<0$$

d) For functions f(x) where there is a singularity and it reverses sign at the singularity, the bisection method may converge on the singularity (Figure 7). An example includes

$$f(x) = \frac{1}{x}$$

where $x_{\ell} = -2$, $x_u = 3$ are valid initial guesses which satisfy

$$f(x_{\ell})f(x_{u}) < 0$$

However, the function is not continuous and the theorem that a root exists is also not applicable.

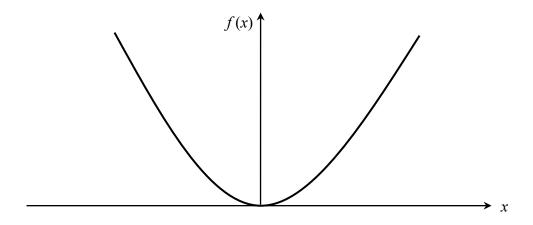


Figure 6 The equation $f(x) = x^2 = 0$ has a single root at x = 0 that cannot be bracketed.

 $^{^{1}}$ A singularity in a function is defined as a point where the function becomes infinite. For example, for a function such as 1/x, the point of singularity is x=0 as it becomes infinite.

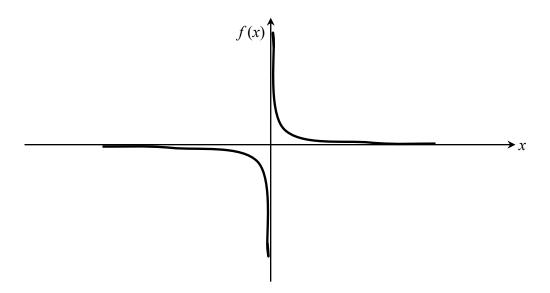


Figure 7 The equation $f(x) = \frac{1}{x} = 0$ has no root but changes sign.

NONLINEAR EQUATIONS					
Topic	Bisection method of solving a nonlinear equation				
Summary	These are textbook notes of bisection method of finding roots of				
	nonlinear equation, including convergence and pitfalls.				
Major	Industrial Engineering				
Authors	Autar Kaw				
Date	November 12, 2012				
Web Site:	http://numericalmethods.eng.usf.edu				