

Bisection Method

Mechanical Engineering Majors

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Bisection Method

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Basis of Bisection Method

Theorem An equation $f(x)=0$, where $f(x)$ is a real continuous function, has at least one root between x_l and x_u if $f(x_l) f(x_u) < 0$.

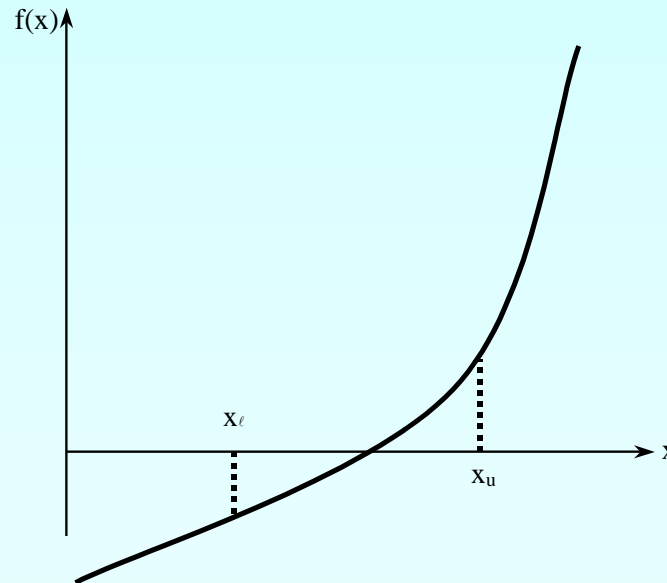


Figure 1 At least one root exists between the two points if the function is real, continuous, and changes sign.

Basis of Bisection Method

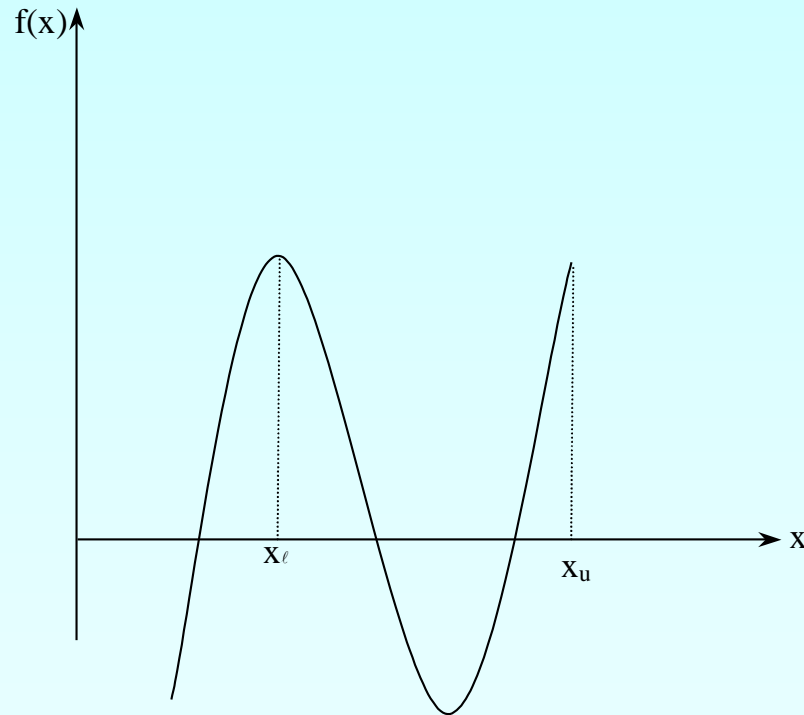


Figure 2 If function $f(x)$ does not change sign between two points, roots of the equation $f(x)=0$ may still exist between the two points.

Basis of Bisection Method

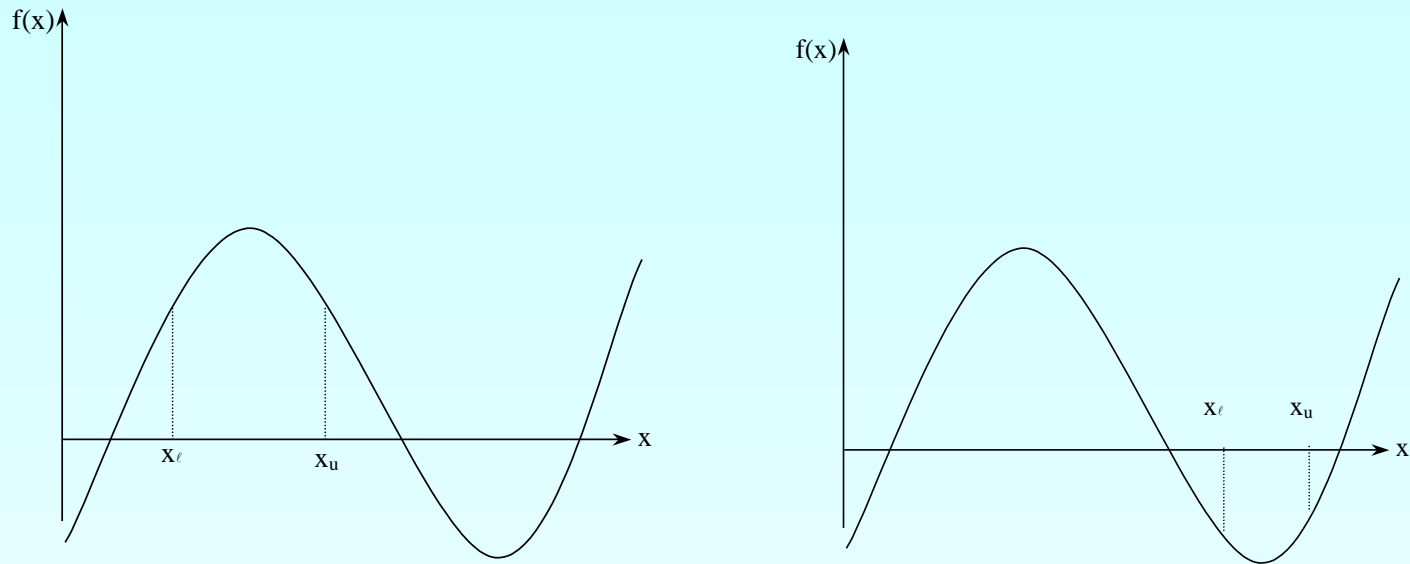


Figure 3 If the function $f(x)$ does not change sign between two points, there may not be any roots for the equation $f(x)=0$ between the two points.

Basis of Bisection Method

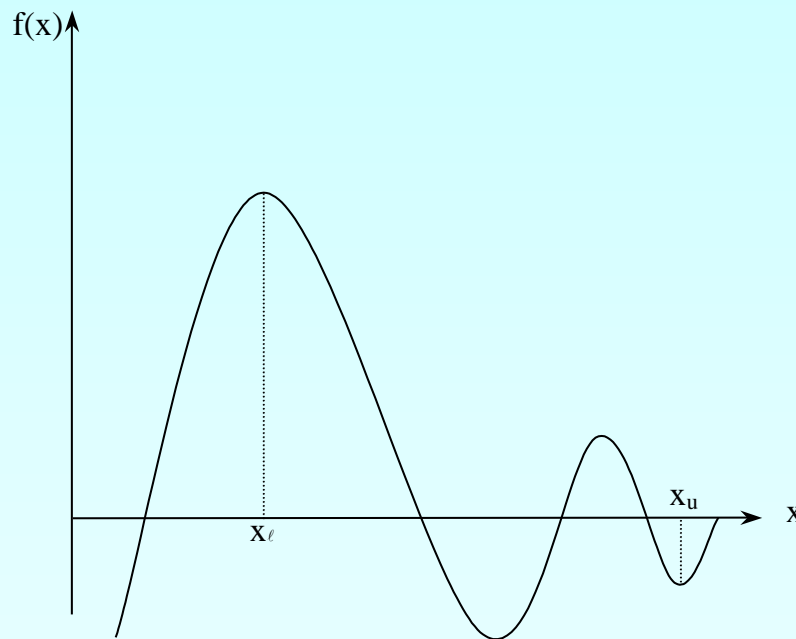


Figure 4 If the function $f(x)$ changes sign between two points, more than one root for the equation $f(x)=0$ may exist between the two points.

Algorithm for Bisection Method

Step 1

Choose x_ℓ and x_u as two guesses for the root such that $f(x_\ell) f(x_u) < 0$, or in other words, $f(x)$ changes sign between x_ℓ and x_u . This was demonstrated in Figure 1.

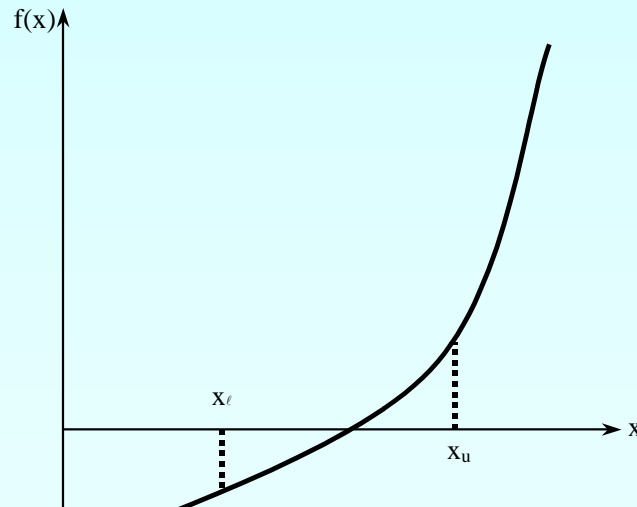


Figure 1

Step 2

Estimate the root, x_m of the equation $f(x) = 0$ as the mid point between x_ℓ and x_u as

$$x_m = \frac{x_\ell + x_u}{2}$$

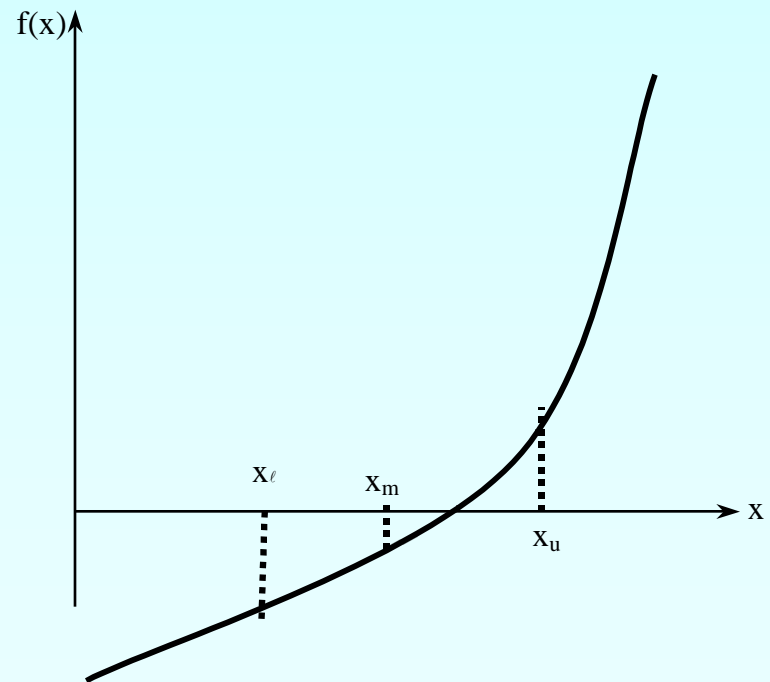


Figure 5 Estimate of x_m

Step 3

Now check the following

- a) If $f(x_l)f(x_m) < 0$, then the root lies between x_l and x_m ; then $x_\ell = x_l$; $x_u = x_m$.
- b) If $f(x_l)f(x_m) > 0$, then the root lies between x_m and x_u ; then $x_\ell = x_m$; $x_u = x_u$.
- c) If $f(x_l)f(x_m) = 0$; then the root is x_m . Stop the algorithm if this is true.

Step 4

Find the new estimate of the root

$$x_m = \frac{x_l + x_u}{2}$$

Find the absolute relative approximate error

$$|\epsilon_a| = \left| \frac{x_m^{new} - x_m^{old}}{x_m^{new}} \right| \times 100$$

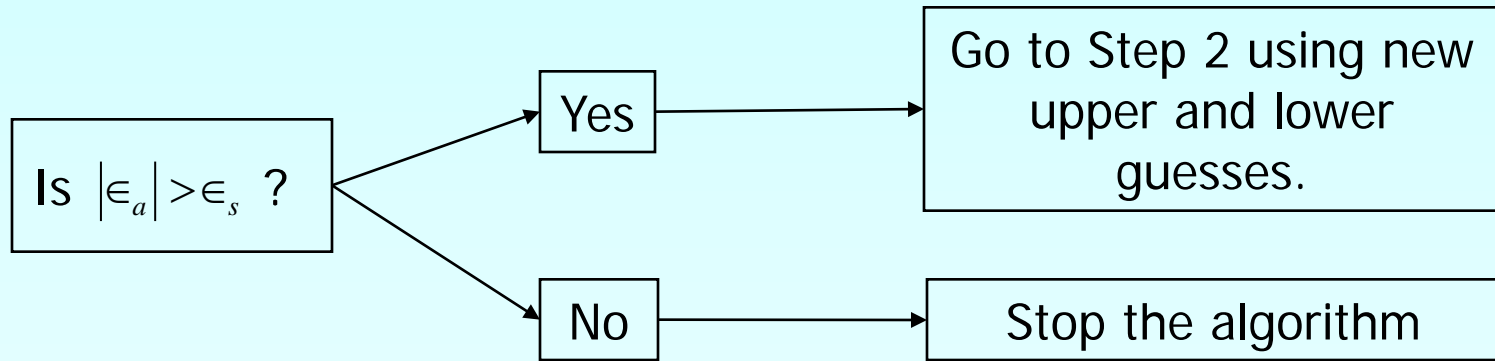
where

x_m^{old} = previous estimate of root

x_m^{new} = current estimate of root

Step 5

Compare the absolute relative approximate error $|\epsilon_a|$ with the pre-specified error tolerance ϵ_s .



Note one should also check whether the number of iterations is more than the maximum number of iterations allowed. If so, one needs to terminate the algorithm and notify the user about it.

Example 1

A trunnion has to be cooled before it is shrink fitted into a steel hub

The equation that gives the temperature x to which the trunnion has to be cooled to obtain the desired contraction is given by the following equation.

$$f(x) = -0.50598 \times 10^{-10} x^3 + 0.38292 \times 10^{-7} x^2 + 0.74363 \times 10^{-4} x + 0.88318 \times 10^{-2} = 0$$

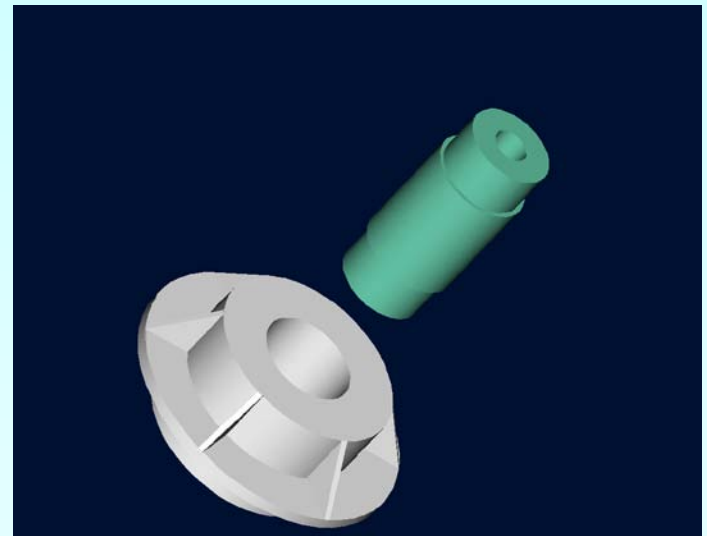
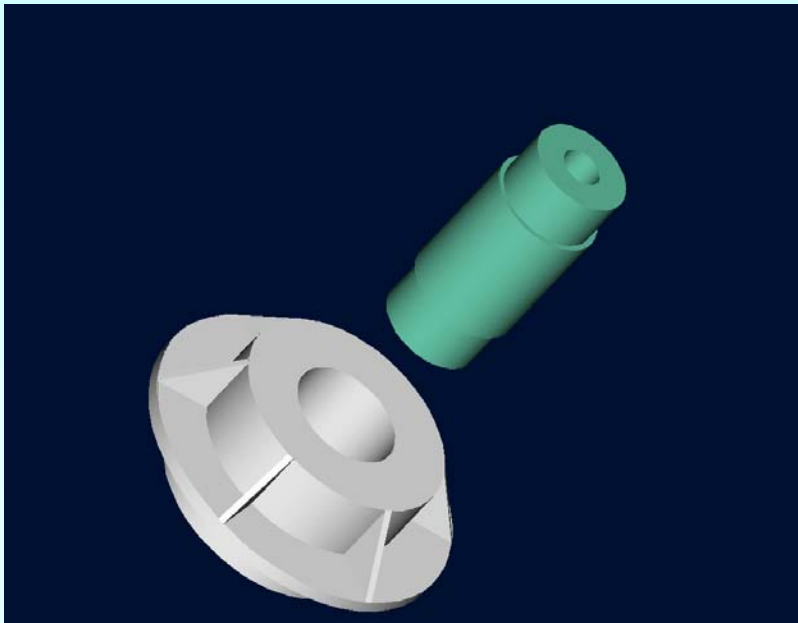


Figure 5 Trunnion to be slid through the hub after contracting.

Example 1 Cont.



Use the bisection method of finding roots of equations

- a) To find the temperature x to which the trunnion has to be cooled. Conduct three iterations to estimate the root of the above equation.
- b) Find the absolute relative approximate error at the end of each iteration, and
- c) the number of significant digits at least correct at the end of each iteration.

Example 1 Cont.

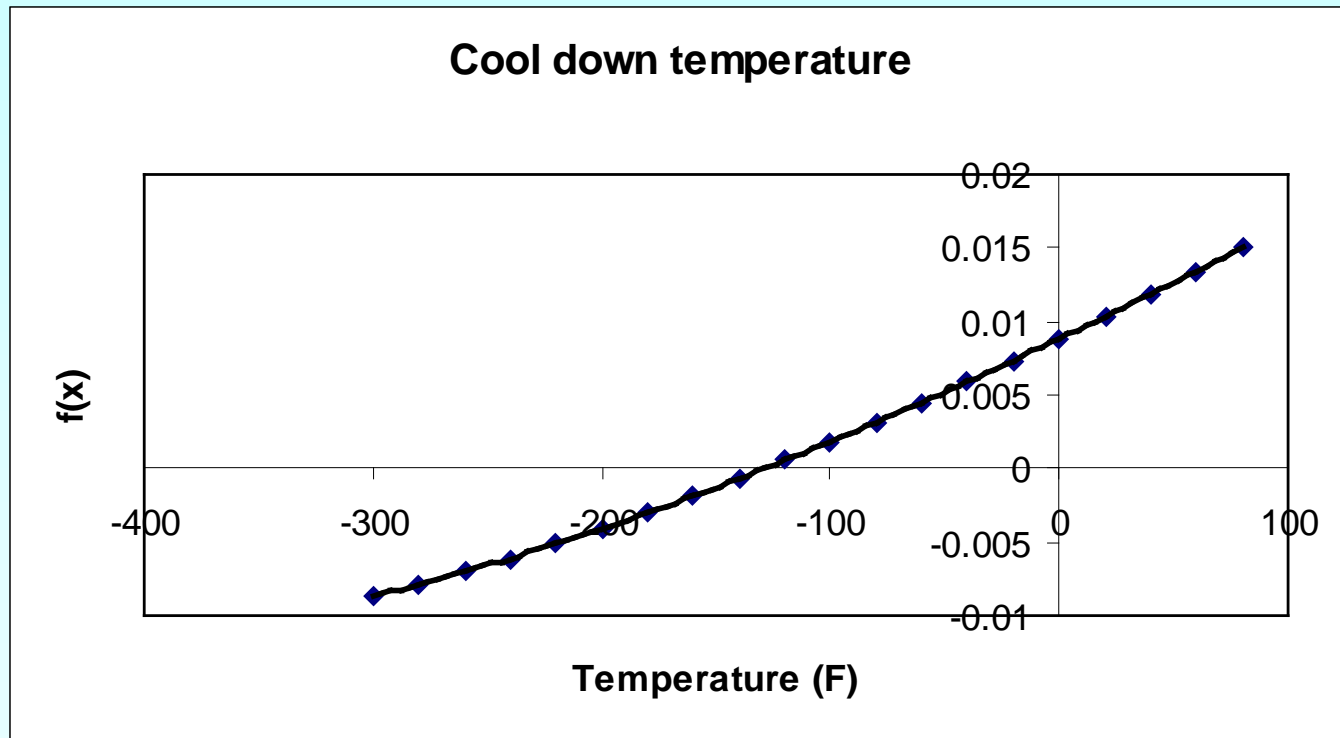
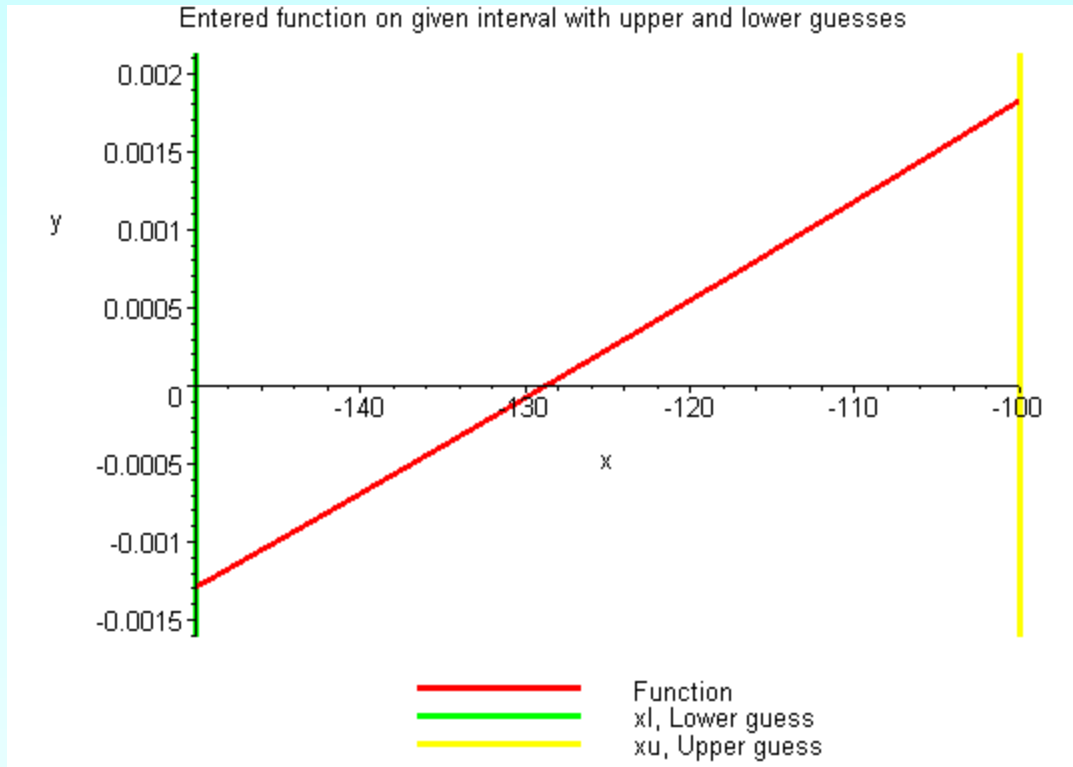


Figure 6 Graph of the function $f(x)$.

$$f(x) = -0.50598 \times 10^{-10} x^3 - 0.38292 \times 10^{-7} x^2 + 0.74363 \times 10^{-4} x + 0.88318 \times 10^{-2} = 0$$

Example 1 Cont.



Choose the bracket

$$x_\ell = -150 \text{ and } x_u = -100$$

$$f(-150) = -1.2903 \times 10^{-3}$$

$$f(-100) = 1.8290 \times 10^{-3}$$

$$f(-100)f(-150) < 0$$

There is at least one root
between x_ℓ and x_u .

Figure 7 Checking that the bracket is valid.

Example 1 Cont.

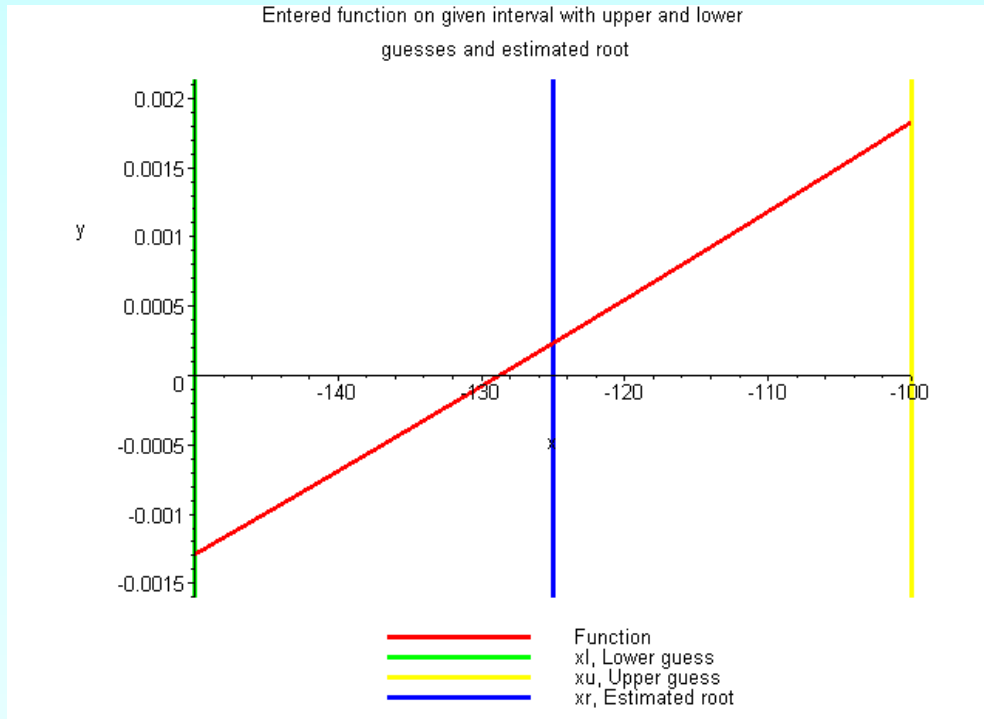


Figure 7 Graph of the estimated root after Iteration 1.

The absolute relative approximate error cannot be calculated, as we do not have a previous approximation.

Iteration 1

The estimate of the root is

$$x_m = \frac{-150 + (-100)}{2} = -125$$

$$f(-125) = 2.3356 \times 10^{-4}$$

$$f(x_l)f(x_m) = f(-150)f(-125) < 0$$

The root is bracketed between x_ℓ and x_m .

The lower and upper limits of the new bracket are

$$x_\ell = -150, x_u = -125$$

Example 1 Cont.

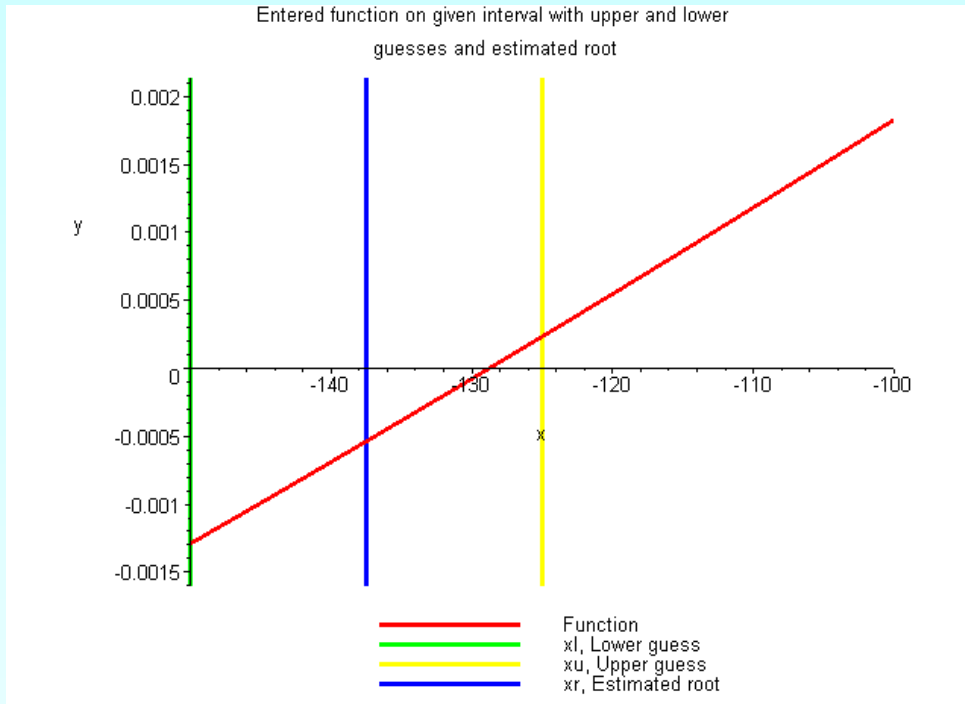


Figure 8 Graph of the estimated root after Iteration 2.

Iteration 2

The estimate of the root is

$$x_m = \frac{-150 + (-125)}{2} = -137.5$$

$$f(-137.5) = -5.3762 \times 10^{-4}$$

$$f(x_l)f(x_m) = f(-150)f(-137.5) > 0$$

The root is bracketed between x_m and x_u .

The lower and upper limits of the new bracket are

$$x_\ell = -137.5, x_u = -125$$

Example 1 Cont.

The absolute relative approximate error at the end of Iteration 2 is

$$\begin{aligned} |\epsilon_a| &= \left| \frac{x_m^{new} - x_m^{old}}{x_m^{new}} \right| \times 100 \\ &= \left| \frac{-137.5 - (-125)}{-137.5} \right| \times 100 \\ &= 9.0909\% \end{aligned}$$

The number of significant digits at least correct in the estimated root is 0.

Example 1 Cont.

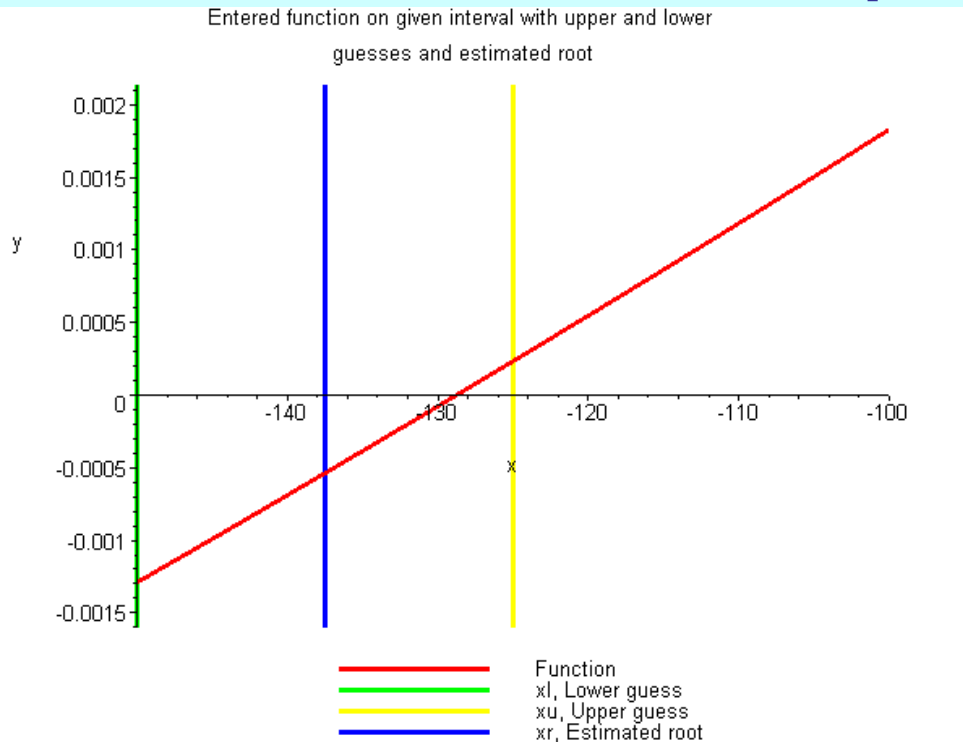


Figure 9 Graph of the estimated root after Iteration 2.

Iteration 3

The estimate of the root is

$$x_m = \frac{-125 + (-137.5)}{2} = -131.25$$

$$f(-131.25) = -1.54303 \times 10^{-4}$$

$$f(x_l)f(x_m) = f(-137.5)f(-131.25) > 0$$

The root is bracketed between x_m and x_u .

The lower and upper limits of the new bracket are

$$x_\ell = -131.25, x_u = -125$$

Example 1 Cont.

The absolute relative approximate error at the end of Iteration 3 is

$$\begin{aligned} |\epsilon_a| &= \left| \frac{x_m^{new} - x_m^{old}}{x_m^{new}} \right| \times 100 \\ &= \left| \frac{-131.25 - (-137.5)}{-131.25} \right| \times 100 \\ &= 4.7619\% \end{aligned}$$

The number of significant digits at least correct in the estimated root is 1.

All Iterations

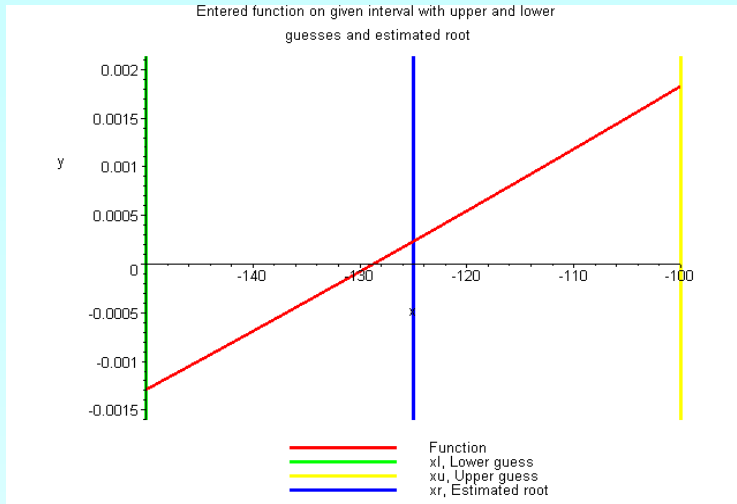


Figure 10 Graph of Iteration 1.

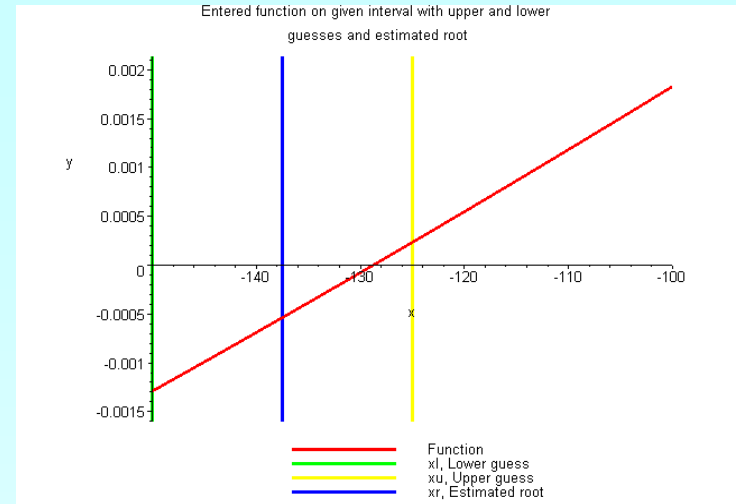


Figure 11 Graph of Iteration 2.

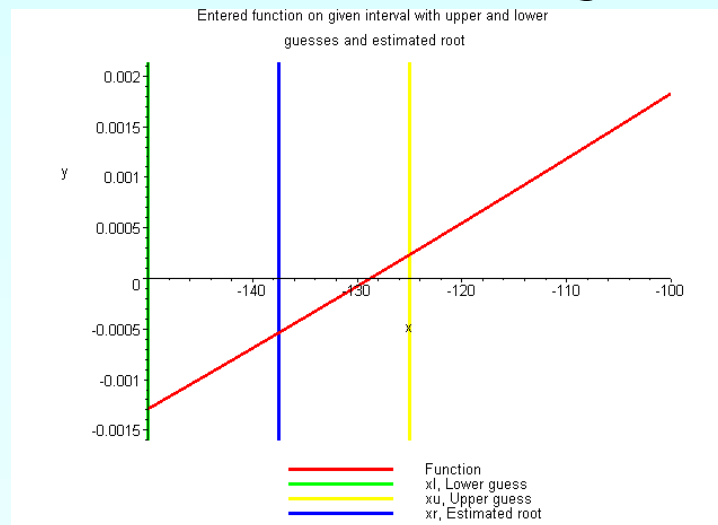


Figure 12 Graph of Iteration 3.

Convergence

Table 1 Root of $f(x)=0$ as function of number of iterations for bisection method.

Iteration	x_l	x_u	x_m	$ \epsilon_a \%$	$f(x_m)$
1	-150	-100	-125	-----	$2.3356 \cdot 10^{-4}$
2	-150	-125	-137.5	9.0909	$-5.3762 \cdot 10^{-4}$
3	-137.5	-125	-131.25	4.7619	$-1.5430 \cdot 10^{-4}$
4	-131.25	-125	-128.13	2.4390	$3.9065 \cdot 10^{-5}$
5	-131.25	-128.13	-129.69	1.2048	$-5.7760 \cdot 10^{-5}$
6	-129.69	-128.13	-128.91	0.60606	$-9.3826 \cdot 10^{-6}$
7	-128.91	-128.13	-128.52	0.30395	$1.4838 \cdot 10^{-5}$
8	-128.91	-128.52	-128.71	0.15175	$2.7228 \cdot 10^{-6}$
9	-128.91	-128.71	-128.81	0.075815	$-3.3305 \cdot 10^{-6}$
10	-128.81	-128.71	-128.76	0.037922	$-3.0396 \cdot 10^{-7}$

Advantages

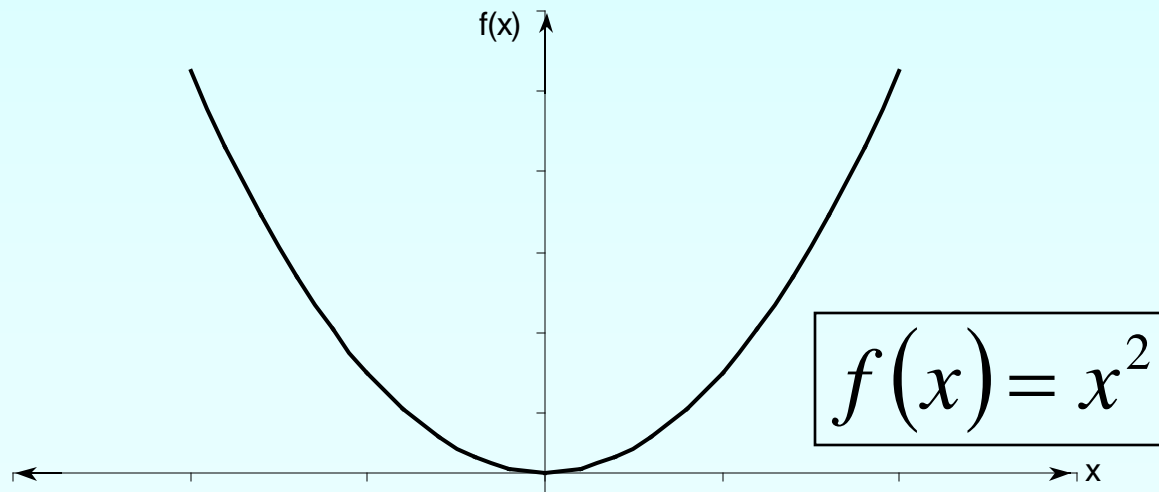
- Always convergent
- The root bracket gets halved with each iteration - guaranteed.

Drawbacks

- Slow convergence
- If one of the initial guesses is close to the root, the convergence is slower

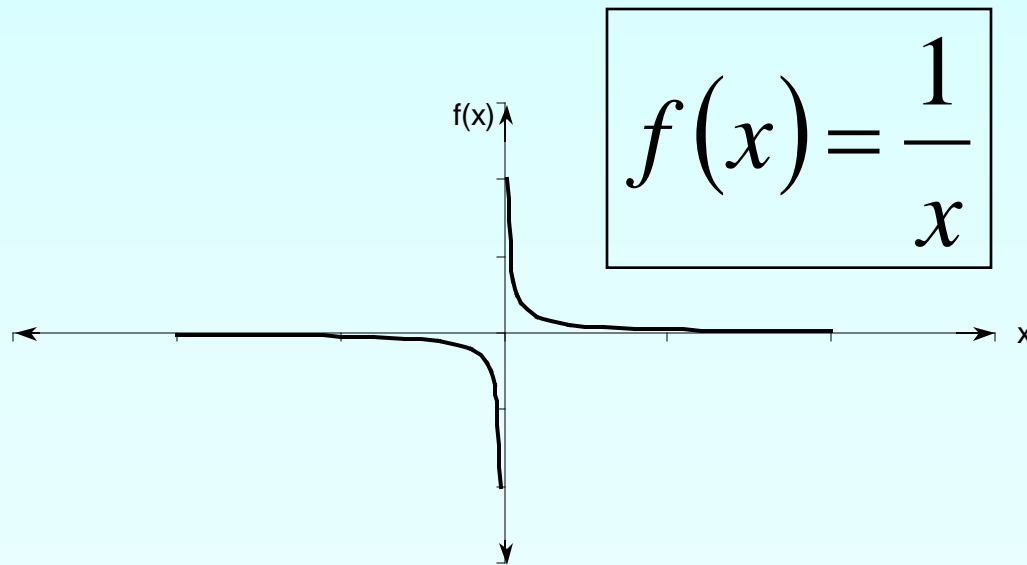
Drawbacks (continued)

- If a function $f(x)$ is such that it just touches the x -axis it will be unable to find the lower and upper guesses.



Drawbacks (continued)

- Function changes sign but root does not exist



Additional Resources

For all resources on this topic such as digital audiovisual lectures, primers, textbook chapters, multiple-choice tests, worksheets in MATLAB, MATHEMATICA, MathCad and MAPLE, blogs, related physical problems, please visit

http://numericalmethods.eng.usf.edu/topics/bisection_method.html

THE END

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