# Simpson's 1/3<sup>rd</sup> Rule of Integration

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Transforming Numerical Methods Education for STEM Undergraduates

# Simpson's 1/3<sup>rd</sup> Rule of Integration

# What is Integration?

#### Integration

The process of measuring the area under a curve.

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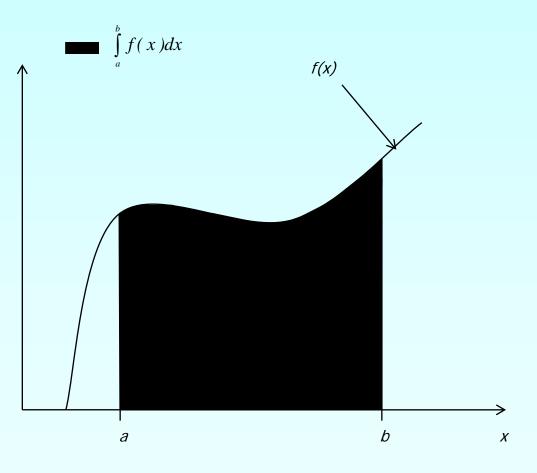
$$I = \int_{a}^{b} f(x) dx$$

Where:

*f(x)* is the integrand

a = lower limit of integration

b= upper limit of integration



### Simpson's 1/3<sup>rd</sup> Rule

## Basis of Simpson's 1/3rd Rule

Trapezoidal rule was based on approximating the integrand by a first order polynomial, and then integrating the polynomial in the interval of integration. Simpson's 1/3rd rule is an extension of Trapezoidal rule where the integrand is approximated by a second order polynomial.

Hence

$$I = \int_{a}^{b} f(x) dx \approx \int_{a}^{b} f_{2}(x) dx$$

Where  $f_2(x)$  is a second order polynomial.

$$f_2(x) = a_0 + a_1 x + a_2 x^2$$

#### Basis of Simpson's 1/3rd Rule

Choose

$$(a, f(a)), \left(\frac{a+b}{2}, f\left(\frac{a+b}{2}\right)\right), \text{ and } (b, f(b))$$

as the three points of the function to evaluate  $a_0$ ,  $a_1$  and  $a_2$ .

$$f(a) = f_2(a) = a_0 + a_1 a + a_2 a^2$$
$$f\left(\frac{a+b}{2}\right) = f_2\left(\frac{a+b}{2}\right) = a_0 + a_1\left(\frac{a+b}{2}\right) + a_2\left(\frac{a+b}{2}\right)^2$$

 $f(b) = f_2(b) = a_0 + a_1 b + a_2 b^2$ 

Solving the previous equations for  $a_0$ ,  $a_1$  and  $a_2$  give

$$a_{0} = \frac{a^{2}f(b) + abf(b) - 4abf\left(\frac{a+b}{2}\right) + abf(a) + b^{2}f(a)}{a^{2} - 2ab + b^{2}}$$

$$a_{1} = -\frac{af(a) - 4af\left(\frac{a+b}{2}\right) + 3af(b) + 3bf(a) - 4bf\left(\frac{a+b}{2}\right) + bf(b)}{a^{2} - 2ab + b^{2}}$$

$$a_{2} = \frac{2\left(f(a) - 2f\left(\frac{a+b}{2}\right) + f(b)\right)}{a^{2} - 2ab + b^{2}}$$

Then

$$I \approx \int_{a}^{b} f_{2}(x) dx$$
$$= \int_{a}^{b} (a_{0} + a_{1}x + a_{2}x^{2}) dx$$

$$= \left[ a_0 x + a_1 \frac{x^2}{2} + a_2 \frac{x^3}{3} \right]_a^b$$

$$= a_0(b-a) + a_1 \frac{b^2 - a^2}{2} + a_2 \frac{b^3 - a^3}{3}$$

Substituting values of  $a_0$ ,  $a_1$ ,  $a_2$  give

$$\int_{a}^{b} f_{2}(x) dx = \frac{b-a}{6} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$$

Since for Simpson's 1/3rd Rule, the interval [a, b] is broken into 2 segments, the segment width

$$h = \frac{b-a}{2}$$

Hence

$$\int_{a}^{b} f_{2}(x) dx = \frac{h}{3} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$$

Because the above form has 1/3 in its formula, it is called Simpson's 1/3rd Rule.

# Example 1

Human vision has the remarkable ability to infer 3D shapes from 2D images. The intriguing question is: can we replicate some of these abilities on a computer? Yes, it can be done and to do this, integration of vector fields is required. The following integral needs to integrated.

$$I = \int_{0}^{100} f(x) dx$$

where

$$f(x) = 0, \ 0 < x < 30$$
  
= -9.1688×10<sup>-6</sup>x<sup>3</sup> + 2.7961×10<sup>-3</sup>x<sup>2</sup> - 2.8487×10<sup>-1</sup>x + 9.6778,  
30 ≤ x ≤ 172  
= 0, \ 172 < x < 200

- a) Use single segment Trapezoidal rule to find the distance covered.
- b) Find the true error,  $E_t$  for part (a).
- c) Find the absolute relative true error,  $|\epsilon_a|$  for part (a).

# Solution

a) 
$$I \approx \frac{b-a}{6} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$$
$$a = 0 \qquad b = 100 \qquad \frac{a+b}{2} = 50$$

$$\approx \left(\frac{100-0}{6}\right) [f(0) + 4f(50) + f(100)]$$

$$\approx \left(\frac{100}{6}\right) \left[0 + 4(1.2784) + (-0.017)\right]$$

 $\approx 84.947$ 

b) The exact value of the above integral is found using Maple for calculating the true error and relative true error.

$$I = \int_{0}^{100} f(x) dx$$
$$= 60.793$$

True Error

 $E_{t} = True \ Value - Approximate \ Value$ = 60.793 - (84.947)= -24.154

c) Absolute relative true error,

$$\left| \in_{t} \right| = \left| \frac{60.793 - (84.947)}{60.793} \right| \times 100$$
$$= 39.732\%$$

#### Multiple Segment Simpson's 1/3rd Rule

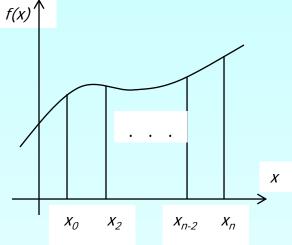
Just like in multiple segment Trapezoidal Rule, one can subdivide the interval [a, b] into n segments and apply Simpson's 1/3rd Rule repeatedly over every two segments. Note that n needs to be even. Divide interval [a, b] into equal segments, hence the segment width

$$h = \frac{b-a}{n} \qquad \qquad \int_{a}^{b} f(x) dx = \int_{x_0}^{x_n} f(x) dx$$

where

$$x_0 = a \qquad \qquad x_n = b$$

$$\int_{a}^{b} f(x) dx = \int_{x_{0}}^{x_{2}} f(x) dx + \int_{x_{2}}^{x_{4}} f(x) dx + \dots$$
$$\dots + \int_{x_{n-4}}^{x_{n-2}} f(x) dx + \int_{x_{n-2}}^{x_{n}} f(x) dx$$



Apply Simpson's 1/3rd Rule over each interval,

$$\int_{a}^{b} f(x) dx = (x_{2} - x_{0}) \left[ \frac{f(x_{0}) + 4f(x_{1}) + f(x_{2})}{6} \right] + \dots + (x_{4} - x_{2}) \left[ \frac{f(x_{2}) + 4f(x_{3}) + f(x_{4})}{6} \right] + \dots$$

$$\dots + (x_{n-2} - x_{n-4}) \left[ \frac{f(x_{n-4}) + 4f(x_{n-3}) + f(x_{n-2})}{6} \right] + \dots$$
$$+ (x_{n-2} - x_{n-4}) \left[ \frac{f(x_{n-2}) + 4f(x_{n-1}) + f(x_n)}{6} \right]$$

 $+(x_{n}-x_{n-2})\left[\frac{f(x_{n-2})+4f(x_{n-1})+f(x_{n})}{6}\right]$ 

Since

$$x_i - x_{i-2} = 2h$$
  $i = 2, 4, ..., n$ 

Then  $\int_{-\infty}^{b} f(x) dx = 2h \left| \frac{f(x_0) + 4f(x_1) + f(x_2)}{6} \right| + \dots$  $+2h\left|\frac{f(x_2)+4f(x_3)+f(x_4)}{\epsilon}\right|+...$  $+2h\left|\frac{f(x_{n-4})+4f(x_{n-3})+f(x_{n-2})}{6}\right|+\dots$  $+2h\left|\frac{f(x_{n-2})+4f(x_{n-1})+f(x_n)}{6}\right|$ 

$$\int_{a}^{b} f(x) dx = \frac{h}{3} [f(x_{0}) + 4 \{f(x_{1}) + f(x_{3}) + \dots + f(x_{n-1})\} + \dots]$$
$$\dots + 2 \{f(x_{2}) + f(x_{4}) + \dots + f(x_{n-2})\} + f(x_{n})\}]$$
$$= \frac{h}{3} \left[ f(x_{0}) + 4 \sum_{\substack{i=1 \ i=0 \ d}}^{n-1} f(x_{i}) + 2 \sum_{\substack{i=2 \ i=even}}^{n-2} f(x_{i}) + f(x_{n}) \right]$$
$$= \frac{b-a}{3n} \left[ f(x_{0}) + 4 \sum_{\substack{i=1 \ i=0 \ d}}^{n-1} f(x_{i}) + 2 \sum_{\substack{i=2 \ i=even}}^{n-2} f(x_{i}) + f(x_{n}) \right]$$

# Example 2

Human vision has the remarkable ability to infer 3D shapes from 2D images. The intriguing question is: can we replicate some of these abilities on a computer? Yes, it can be done and to do this, integration of vector fields is required. The following integral needs to integrated.

$$I = \int_{0}^{100} f(x) dx$$
  

$$f(x) = 0, \ 0 < x < 30$$
  

$$= -9.1688 \times 10^{-6} x^{3} + 2.7961 \times 10^{-3} x^{2} - 2.8487 \times 10^{-1} x + 9.6778,$$
  

$$30 \le x \le 172$$
  

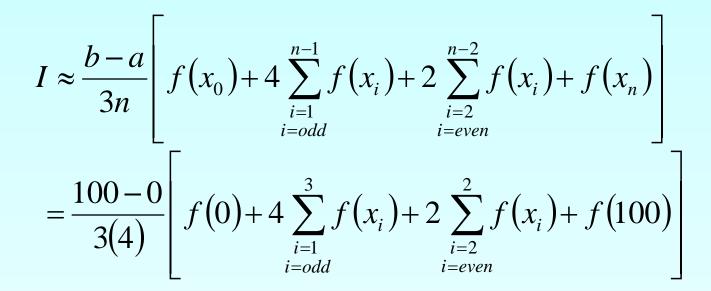
$$= 0, \ 172 < x < 200$$

- a) Use four segment Simpson's 1/3rd Rule to find the approximate value of x.
- b) Find the true error,  $E_t$  for part (a). c) Find the absolute relative true error,  $|\epsilon_a|$  for part (a).

#### Solution

a) Using n segment Simpson's 1/3rd Rule,

$$h = \frac{100 - 0}{4} = 25$$
  
So  $f(x_0) = f(0)$   
 $f(x_1) = f(0 + 25) = f(25)$   
 $f(x_2) = f(25 + 25) = f(50)$   
 $f(x_3) = f(50 + 25) = f(75)$   
 $f(x_4) = f(x_n) = f(100)$ 



$$=\frac{100}{12}\left[f(0) + 4f(x_1) + 4f(x_3) + 2f(x_2) + f(100)\right]$$

cont.

$$=\frac{25}{3}\left[f(0) + 4f(25) + 4f(75) + 2f(50) + f(100)\right]$$

$$=\frac{25}{3}\left[0+4(0)+4(0.17253)+2(1.2784)+(-0.017000)\right]$$

= 26.917

b) In this case, the true error is

 $E_t = 60.793 - (26.917) = 33.873$ 

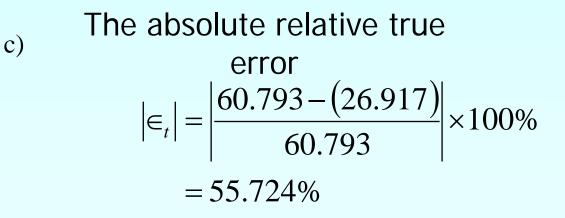


Table 1: Values of Simpson's 1/3rd Rule for Example 2 with multiple segments

| n  | Approximate Value | $E_t$   | $ \epsilon_t \%$ |
|----|-------------------|---------|------------------|
| 2  | 84.947            | -24.154 | 39.732           |
| 4  | 26.917            | 33.876  | 55.724           |
| 6  | 66.606            | -5.8138 | 9.5633           |
| 8  | 62.318            | -1.5252 | 2.5088           |
| 10 | 85.820            | -25.023 | 41.169           |

The true error in a single application of Simpson's 1/3rd Rule is given as

$$E_{t} = -\frac{(b-a)^{5}}{2880} f^{(4)}(\zeta), \quad a < \zeta < b$$

In Multiple Segment Simpson's 1/3rd Rule, the error is the sum of the errors in each application of Simpson's 1/3rd Rule. The error in n segment Simpson's 1/3rd Rule is given by

$$\begin{split} E_1 &= -\frac{(x_2 - x_0)^5}{2880} f^{(4)}(\zeta_1) = -\frac{h^5}{90} f^{(4)}(\zeta_1), \quad x_0 < \zeta_1 < x_2 \\ E_2 &= -\frac{(x_4 - x_2)^5}{2880} f^{(4)}(\zeta_2) = -\frac{h^5}{90} f^{(4)}(\zeta_2), \quad x_2 < \zeta_2 < x_4 \end{split}$$

$$E_{i} = -\frac{(x_{2i} - x_{2(i-1)})^{5}}{2880} f^{(4)}(\zeta_{i}) = -\frac{h^{5}}{90} f^{(4)}(\zeta_{i}), \quad x_{2(i-1)} < \zeta_{i} < x_{2i}$$

$$E_{\frac{n}{2}-1} = -\frac{(x_{n-2} - x_{n-4})^5}{2880} f^{(4)} \left(\zeta_{\frac{n}{2}-1}\right) = -\frac{h^5}{90} f^{(4)} \left(\zeta_{\frac{n}{2}-1}\right), \quad x_{n-4} < \zeta_{\frac{n}{2}-1} < x_{n-2}$$

$$E_{\frac{n}{2}} = -\frac{(x_n - x_{n-2})^5}{2880} f^4 \left(\zeta_{\frac{n}{2}}\right) = -\frac{h^5}{90} f^{(4)} \left(\zeta_{\frac{n}{2}}\right) , \quad x_{n-2} < \zeta_{\frac{n}{2}} < x_n$$

Hence, the total error in Multiple Segment Simpson's 1/3rd Rule is

$$E_{t} = \sum_{i=1}^{\frac{n}{2}} E_{i} = -\frac{h^{5}}{90} \sum_{i=1}^{\frac{n}{2}} f^{(4)}(\zeta_{i}) = -\frac{(b-a)^{5}}{90n^{5}} \sum_{i=1}^{\frac{n}{2}} f^{(4)}(\zeta_{i})$$
$$= -\frac{(b-a)^{5}}{90n^{4}} \sum_{i=1}^{\frac{n}{2}} f^{(4)}(\zeta_{i})}{n}$$

The term  $\frac{\sum_{i=1}^{n} f^{(4)}(\zeta_i)}{n}$  is an approximate average value of  $f^{(4)}(x), a < x < b$ 

Hence

$$E_t = -\frac{(b-a)^5}{90n^4} \overline{f}^{(4)}$$

where

$$\overline{f}^{(4)} = \frac{\sum_{i=1}^{n} f^{(4)}(\zeta_i)}{n}$$

## **Additional Resources**

For all resources on this topic such as digital audiovisual lectures, primers, textbook chapters, multiple-choice tests, worksheets in MATLAB, MATHEMATICA, MathCad and MAPLE, blogs, related physical problems, please visit

http://numericalmethods.eng.usf.edu/topics/simpsons\_ 13rd\_rule.html

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